

Design and Performance of Selected Classes of Tanner Codes

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Abstract—We study the design of structured Tanner codes with low error-rate floors on the binary additive white Gaussian noise channel (BAWGNC) and the binary erasure channel (BEC). The design technique involves the “doping” of standard LDPC protographs, meaning Hamming or recursive systematic convolutional (RSC) code constraints are used together with single-parity-check (SPC) constraints to construct a code’s protograph. We show that the doping of a “good” graph with Hamming or RSC codes is a pragmatic approach that frequently results in a code with a good threshold and very low error-rate floor. We focus on low-rate Tanner codes, in part because the design of low-rate, low-floor LDPC codes is particularly difficult.

I. INTRODUCTION

An LDPC code [1] is defined as an (n, k) linear block code whose parity check matrix H possesses a low density of non-zero elements. The $m \times n$ matrix H can be represented as a bipartite graph (Tanner graph) with n variable nodes and m single-parity-check (SPC) nodes. A generalization of these codes was suggested by Tanner in [2], for which subsets of the variable nodes obey a more complex constraint than an SPC constraint, such as a Hamming code constraint. There are at least two advantages to employing constraint nodes with constraints more complex than a simple parity check. First, more complex constraints tend to lead to larger minimum distances. Second, the employment of more complex constraint nodes permits a simpler Tanner graph so that deleterious graphical properties are more easily avoided. Both of these advantages lead to a lower error-rate floor.

One successful instance of a Tanner code is the turbo product code (TPC) [3]. Other special cases of Tanner codes were studied in [4], [5], [8] where the constraint nodes correspond to Hamming codes or short LDPC codes. Also, in [6] codes are built by applying BCH or Reed-Solomon code constraints to variable node subsets, and in [7] recursive systematic convolutional (RSC) codes are used as constraints. The RSC-LDPC codes in this work are more general in the sense that different constraint nodes can be used to construct codes and the graph structure is generally more flexible.

Liva and Ryan in [9], [10] present a more general case of Tanner codes in [5] called Hamming-doped LDPC codes (HD-LDPC). This generalization allows more than one type of constraint node in the graph as well as irregularity among the node degrees. The doping refers to the fact that the design

approach involves inserting Hamming constraint nodes into a Tanner graph or a protograph [11] in place of selected SPC nodes. (A protograph will be defined in Section III.) In this paper, we consider the doping of protographs using either Hamming nodes or RSC nodes; we will call the latter code type RSC-LDPC codes. When referring generically to such a code, we will use doped LDPC code and Tanner code interchangeably. We will also refer to a code that resides at a constraint node as a component code (in contrast with Tanner’s “subcode”), and we use constraint node and component-code node interchangeably. Low-rate codes find application in deep-space communications, wireless communications, and file transfer over packet-erasure channels. We demonstrate via computer simulations low-rate HD-LDPC and RSC-LDPC codes with very low error floors on the BAWGNC and the BEC, even for code lengths less than 1000 bits.

The paper proceeds as follows. In the next section, we present an overview of the construction of Hamming- and RSC-doped LDPC codes based on protographs. Section III presents four example code family designs. In Section IV, we present simulation results, for the BAWGNC and BEC, of the codes that we have designed.

II. OVERVIEW OF THE DESIGN TECHNIQUE

The graph of a Tanner code has n variable nodes and m_c constraint nodes. The connections between the set of variable nodes and constraint nodes V and C is given by an $m_c \times n$ adjacency matrix Γ . For an LDPC code, the adjacency matrix Γ and the parity-check matrix H are identical. For a Tanner code, knowledge of the parity-check matrices of the component codes is also required.

In this paper, we consider only Hamming or RSC component codes in addition to the more common SPC component codes. Because the parity-check matrices for SPC and Hamming codes are straightforward, we discuss only the parity-check matrices for (possibly punctured) rate-1/2 finite-length RSC codes which will be used to dope graphs. For a memory- ν , rate-1/2 RSC code with generator polynomials $g_1(D) = g_{10} + g_{11}D + \dots + g_{1\nu}D^\nu$ and $g_2(D) = g_{20} + g_{21}D + \dots + g_{2\nu}D^\nu$, the corresponding parity-check matrix is

$$H(D) = \begin{bmatrix} g_2(D) & g_1(D) \end{bmatrix}. \quad (1)$$

Because we consider finite block lengths, the binary parity-

check matrix for such a code is given by

$$H = \begin{bmatrix} g_{20} & g_{10} & 0 & 0 & 0 & 0 & \dots \\ g_{20} & g_{10} & g_{20} & g_{10} & 0 & 0 & \dots \\ \vdots & \vdots & g_{20} & g_{10} & & & \\ g_{2\nu} & g_{1\nu} & \vdots & \vdots & & & \\ 0 & 0 & g_{2\nu} & g_{1\nu} & & & \\ 0 & 0 & 0 & 0 & & \ddots & \\ \vdots & \vdots & \vdots & \vdots & & & \end{bmatrix}, \quad (2)$$

To find the rate of a doped graph with n variable nodes and m_c constraint nodes, note that each component-code contributes $(1 - R_i)n_i$ redundant bits, where n_i and R_i are the length and rate of the i^{th} component-code, respectively. Consequently, the total number of redundant bits in the code cannot exceed $m = \sum_{i=1}^{m_c} (1 - R_i)n_i$, and so the number of information bits in the code will be at least $n - m$. This implies that the code rate satisfies $R_c \geq 1 - \frac{m}{n}$, with equality when the check equations are independent.

The parameters in standard LDPC code design which most affect code performance with iterative decoding are the degree distributions of the node types, the topology of the graph (e.g., to maximize girth), and the minimum distance, d_{\min} . For the design of Tanner codes, decisions must also be made on the types and multiplicities of component codes to be used. The choice of component code types and their multiplicities is dictated by the code rate and complexity requirements. Regarding complexity, we consider only Hamming codes for which the number of parity bits is $(1 - R_i)n_i \leq 4$ and only RSC codes for which the number of trellis states is at most eight. Note that this constraint on the Hamming code family limits the number of states in the time-varying BCJR trellis [12] to be at most 16.

As for LDPC codes, the topology of the graph for a Tanner code should be free of short cycles. Obtaining optimal or near-optimal degree distributions for the graphs of Tanner codes can proceed as for LDPC codes, using EXIT charts [13], for example. In this paper, we instead follow the pragmatic design approach introduced in [9], [10], which starts with a protograph that is known to have a good decoding threshold and replaces selected SPC nodes with either Hamming or RSC nodes. Although we provide no proof, the substitution of these more complex nodes tends to increase minimum distance, as shown by simulations. Further, it leads to a smaller adjacency matrix since multiple SPC nodes are replaced by a single component code node. The implication of a smaller adjacency matrix is that short cycles and other deleterious graphical properties are more easily avoided.

III. EXAMPLE DOPED LDPC CODE DESIGNS

A protograph [14], [11] is a relatively small bipartite graph from which a larger graph can be obtained by a copy-and-permute procedure: the protograph is copied q times, and then the edges of the individual replicas are permuted among the replicas (under restrictions described below) to obtain a single, large graph. Of course, the edge connections are specified by the adjacency matrix Γ .

Note that the edge permutations cannot be arbitrary. In particular, the nodes of the protograph are labeled so that if variable node A is connected to constraint node B in the protograph, then variable node A in a replica can only connect to one of the q replicated B constraint nodes. Doing so preserves the decoding threshold properties of the protograph. A protograph can possess parallel edges, i.e., two nodes can be connected by more than one edge. The copy-and-permute procedure must eliminate such parallel connections in order to obtain a derived graph appropriate for a parity-check matrix.

It is convenient to choose an adjacency matrix Γ as an $M_c \times n_c$ array of $q \times q$ weight-one circulant matrices (some of which may be the $q \times q$ zero matrix). We will call each row of permutation matrices a *block row* which we observe has q rows and $n = qn_c$ columns. We note that there is one block row for each constraint node of the protograph. We note also that the number of nonzero permutation matrices in a block row is simultaneously equal to the degree of its corresponding constraint nodes and the common length of the nodes' component codes.

Since there is one matrix H_i for each block row of Γ (for the i^{th} component code), we need only discuss the i^{th} block row. Let H_i be $m_i \times n_i$. Then for each row in the i^{th} block row, replace the n_i ones in the row by the corresponding n_i columns of H_i . This expands the i^{th} block row from $q \times n$ to $qm_i \times n$. (For the special case of an SPC constraint node, $m_i = 1$ and the row block is not expanded.) Once this process has been applied to each block row, the resulting parity-check matrix H for the Tanner code will be $\sum_i qm_i \times n$. Because Γ is block circulant, the resulting matrix H can also be put in a block-circulant form (thus, the Tanner code will be quasi-cyclic) [10].

For the case when Γ is not an array of circulants, the H matrix can be obtained via a process analogous to the one above. Γ in this case corresponds to a random permutation on the edges of the protograph replicas, but two constraints are taken in considerations: the protograph structure and the girth of the graph.

In the remainder of this section, we present several HD-LDPC and RSC-LDPC codes whose design relies on doping protographs. In Section IV we present selected simulation results for these codes on the BAWGNC and BEC.

Code Design 1: Rate-1/6 HD-LDPC Code. The doped protograph for a rate-1/6 HD-LDPC code is shown in Figure 1. The protograph displays a single information bit, u_0 , five parity bits p_0 to p_4 , two SPC nodes, and a (6,3) shortened Hamming code. The initial protograph that we doped was a rate-1/4 ARA protograph [15], but with minor modification.

The (6,3) Hamming code was selected because it leads to the targeted rate of 1/6, it has a low-complexity BCJR decoder, and its H matrix-based graph is free of 4-cycles so that belief propagation is an option. Note also that the addition of the Hamming node has the effect of amplifying the minimum distance of the eventual code (after copying and permuting). This is because there will be q copies of the Hamming node whose codewords have a minimum distance of three. Section IV presents an example code based on this protograph together with its performance (a pseudo-random adjacency matrix is

used).

Code Design 2: Rate-1/6 RSC-LDPC Code. The idea of adding a component code node to amplify weight (hence, d_{min}) led us to consider RSC nodes, particularly since RSC codes produce large weight for low-weight inputs. Since a rate-1/2 RSC code can have any even length, we must consider in the design of an RSC-doped protograph what this length should be. Figure 2 accommodates an unterminated $(6T, 3T)$ RSC component code, where T is a design parameter, so that the overall protograph has T inputs and $6T$ outputs. The $6T$ outputs are represented by all of the circles in Figure 2, some of which are obscured; the RSC node in Figure 2 has $3T$ inputs and $3T$ outputs. Notice that this figure contains T equivalent *sub-protographs*. In the copy-and-permute procedure, we ignore the fact that these were formerly protographs, and apply the copy-and-permute rules only to the overall protograph.

We point out that codes based on this protograph are turbo-like [16] in the sense that copies of the information bits are permuted and distributed over T accumulators, and then part of their outputs together with the remaining information bits are permuted and fed to the RSC code encoder. One major difference, however, is that the present code uses multiple short RSC code blocks rather than one or two long RSC code blocks. The rate-1/6 RSC-LDPC codes presented in Section IV utilize pseudo-random adjacency matrices.

Code Design 3: Rate-1/2 HD-LDPC Code. The protograph in Figure 3 corresponds to a rate-1/2 HD-LDPC code. It consists of two (15,11) Hamming component codes and 15 variable nodes. One of the protograph's variable nodes is punctured to achieve the desired rate. Further, the two code-components are not identical. Specifically,

$$H_1 = [M_1 \ M_2] = \begin{bmatrix} 10101010 & 1010101 \\ 01100110 & 0110011 \\ 00011110 & 0001111 \\ 00000001 & 1111111 \end{bmatrix}$$

and $H_2 = [M_2 \ M_1]$, where the definitions of M_1 and M_2 are evident. The benefit of permuting the bits of identical component codes was pointed out by Tanner [2].

A rate-1/2 (2044,1022) Tanner code can be constructed from the protograph of Figure 3 as follows. First, make $q = 146$ total replicas of the protograph. This yield a graph with $n = (15)(146) = 2190$ bit nodes and $m_c = 292$ check nodes. The number of parity bits for the code is $m = 292(15 - 11) = 1168$ so that the resulting code is (2190,1022). For the code presented in Section IV, Γ is an array of $q \times q$ circulants, in which case, the code quasi-cyclic. A rate-1/2 (2044,1022) quasi-cyclic Tanner code can be obtained by puncturing the first 146 bits of each codeword (corresponding to the first column of circulants of Γ).

Code Design 4: Rate-1/5 HD-LDPC Codes. A rate-1/5 HD-LDPC code can be derived from Code 1, which has rate-1/6, by puncturing the systematic bits. That is, the protograph node u_0 in Figure 1 will represent punctured bits. A second rate-1/5 HD-LDPC code may be obtained by removing the leftmost (diagonal) edge in the protograph of Figure 1, to obtain a new protograph (where again node u_0 is punctured). We will call these designs Design 4a and Design

4b, respectively. We will see in the next section that the first design leads to lower floors whereas the second leads to better decoding thresholds.

IV. SIMULATION RESULTS

The decoders we employ for the Tanner codes we have designed are standard message-passing decoders, with soft-input soft-output (SISO) decoders used at the non-SPC constraint nodes. The choice of the SISO decoder for non-SPC constraint codes depends on the constraint code type. For RSC codes, we use the BCJR decoder [17]. In HD-LDPC codes, the Hamming constraints can be replaced by their equivalent SPC equations. However, except for the (6,3) shortened Hamming code, the large number of 4-cycles the resultant graph degrades the performance of the SPA decoder. Alternatively, for the Hamming nodes, we can use the BCJR decoder applied to the BCJR trellis [12].

We now present several simulation results for different doped-LDPC codes on the BAWGNC. First, we designed a (600, 100) HD-LDPC code based on the protograph in Figure 1 and three (600, 100) RSC-LDPC codes based on the protograph in Figure 2 (Code Designs 1 and 2). The three RSC-LDPC codes correspond to three different values of the parameter T : $T = 2, 4$, and 8 . All of these codes were constructed using random permutations on the edges of their protographs, but two constraints are taken into consideration: the protograph structure and the girth of the graph. The progressive edge growth construction in [18] is used to give the required girth, which is eight for all loops that have only SPC nodes. On the other hand, loops that include Hamming or RSC nodes can be of length less than eight.

A comparison between the frame error rate (FER) curves of these codes and the random coding bound (RCB) is presented in Figure 4. The iterative decoder described above was used, where BCJR decoders are used to decode the Hamming and RSC component codes. The maximum number of iterations is $I_{max} = 50$ and 20 error events were collected at each E_b/N_0 value on each curve, except for the point at 4.5 dB of the $T = 8$ RSC-LDPC curve where only three error events occurred during the decoding of 7.26×10^8 codewords. Note that the floor for almost every code is quite low, even though the code length is 600. Note also the lowest floor occurs for the $T = 8$ RSC-LDPC code, which shows no evidence of a floor down to $FER \approx 10^{-9}$. This code is about 1.3 dB from the random coding bound at $FER = 10^{-4}$.

Figure 5 shows the error rate performance curves of the (2044, 1022) quasi-cyclic HD-LDPC code (Code Design 3) on the BAWGNC. The Hamming component codes were decoded using the BCJR decoder and the overall decoder employed a maximum of $I_{max} = 50$ iterations. The code performance is within 1 dB of the random coding bound and has no floor down to $FER \approx 5 \times 10^{-8}$.

For Code Design 4, we designed two 1/5(8960,1792) quasi-cyclic codes per the Code Design 4a and 4b procedures described above. In Figure 6, the frame error rate performances (with $I_{max} = 200$) of the two codes on the BAWGNC are compared with that of the 1/6(8960,1786) convolutional

turbo code standardized by CCSDS [20]. For the turbo code, $I_{max} = 10$ [21], which is usually sufficient to achieve near the maximum possible coding gain for turbo codes. The Tanner codes possess a slower convergence speed as a function of iteration count (due to the choice of protographs with excellent thresholds), but this does not necessarily imply a slower decoder since the constraint nodes are less complex than those of the turbo code, and each iteration can be performed quickly. Further, parallel processing is more amenable in a Tanner code. Code 4a is characterized by an extremely low floor. Code 4b is characterized by excellent performance in the waterfall region: at an FER = 10^{-3} the code is less than 0.5 dB away from the random coding bound, and exhibits almost the same performance of the rate-1/6 turbo code (even though the Tanner code has a higher rate). Code 4b is superior to Code 4a at FER = 10^{-3} by more than 0.2 dB, but it has an error floor just below 10^{-3} . Code 4a reaches a frame error rate close to 10^{-6} without a floor, within 0.8 dB of the bound.

We have also simulated the (600,100) codes and the (2044,1022) code on the BEC using two decoder types. The first decoder, denoted MPA, is a standard iterative message-passing algorithm BEC decoder tailored to the parity-check matrices H of the codes. The second decoder, denoted ML-MPA, employs maximum-likelihood decoding at the Hamming and RSC nodes and is tailored to the constraint matrices Γ of the codes. Figure 7 displays the performance of the (600,100) codes on the BEC with these two decoder types together with a (600,100) random coding bound. It is also observed that the RSC-LDPC code with $T = 8$ has low floors for both decoders and that the ML-MPA decoder is superior to the MPA decoder. All other codes have floors for both decoders. Similarly, for the (2044,1022) code, the ML-MPA decoder is superior to the MPA decoder as seen in Figure 8. It is difficult to discern the quality of these code based on their gaps to the bounds. An alternative way to do this is to note that the (600,100) code achieves an FER of 10^{-5} when the erasure rate $\varepsilon = 0.645$ and the (2044,1022) code achieves this FER when $\varepsilon = 0.345$. Based on the same random coding bound, these values of ε correspond to the "optimal" code rates 0.264 and 0.604. Thus, the "throughput losses" for these codes, relative to the optimal throughputs given by the random coding bound, are $(0.264 - 0.166)/(0.166) = 59\%$ and $(0.604 - 0.5)/0.5 = 20.8\%$.

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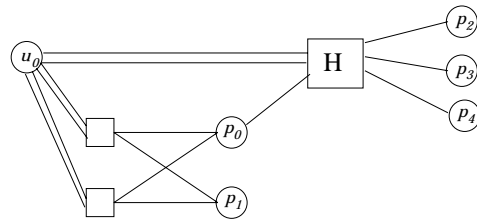


Fig. 1. Rate-1/6 HD-LDPC protograph.

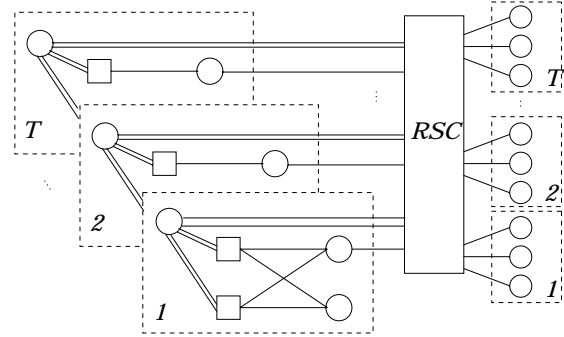


Fig. 2. Rate-1/6 RSC-LDPC protograph.

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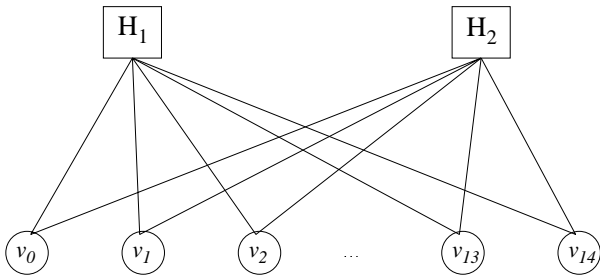


Fig. 3. Rate-1/2 HD-LDPC protograph.

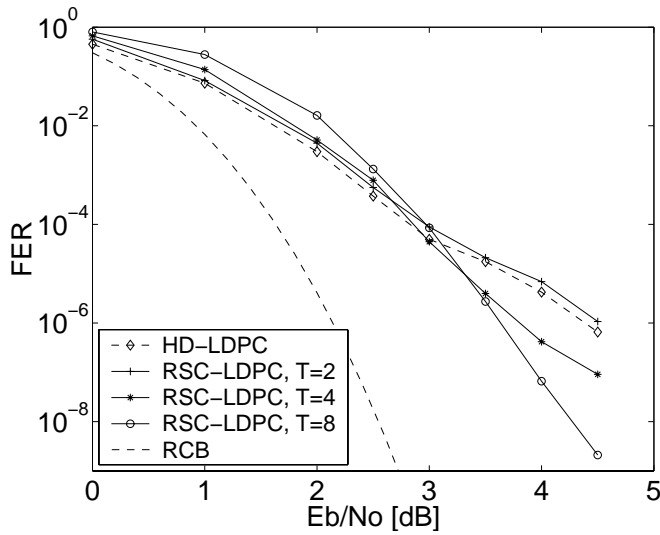


Fig. 4. Frame error rate comparison between (600,100) HD-LDPC and RSC-LDPC codes at different T , $I_{max} = 50$.

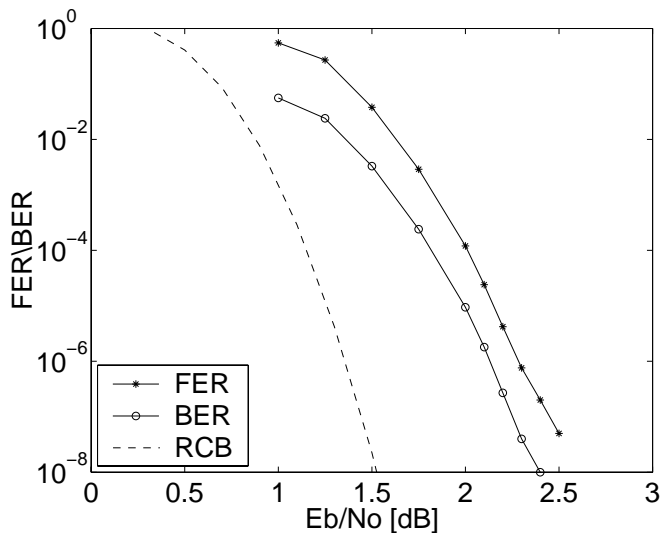


Fig. 5. Performance of (2044,1022) HD-LDPC code compared to the random coding bound, $I_{max} = 50$.

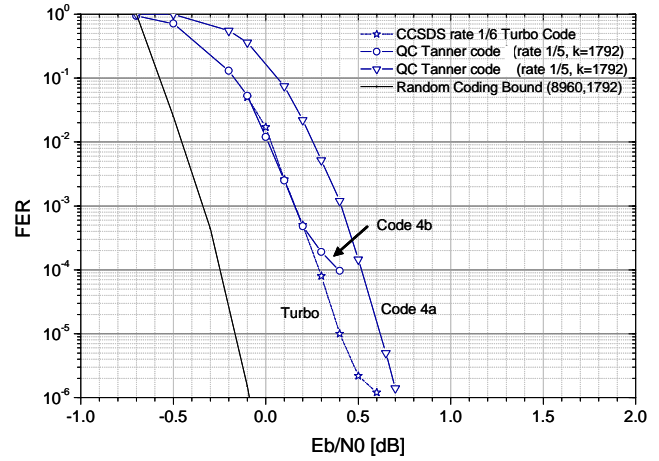


Fig. 6. Performances of Codes 4a and 4b compared to that of CCSDS turbo code.

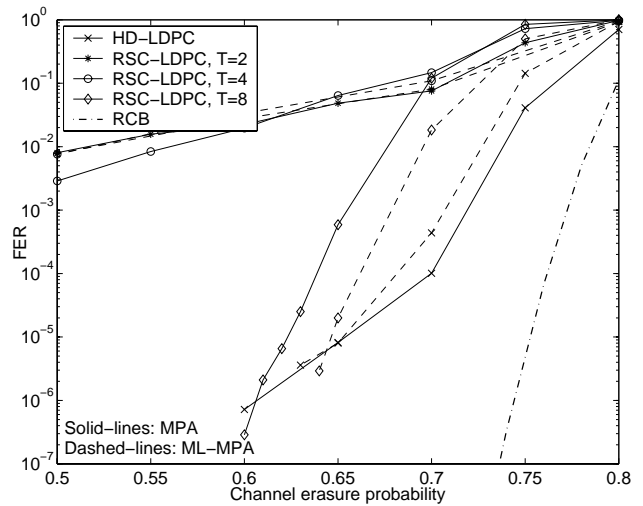


Fig. 7. Performance of the (600,100) codes of Fig. 4 on the BEC.

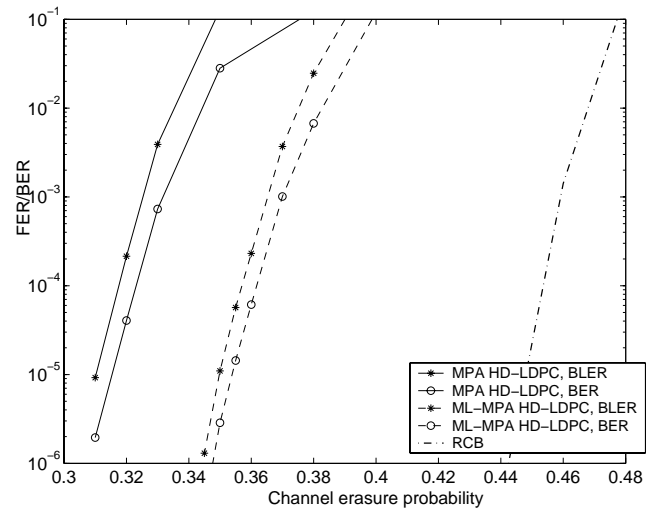


Fig. 8. Performance of the (2044,1022) code of Fig. 5 on the BEC.